

Ray Tracing

Image formation

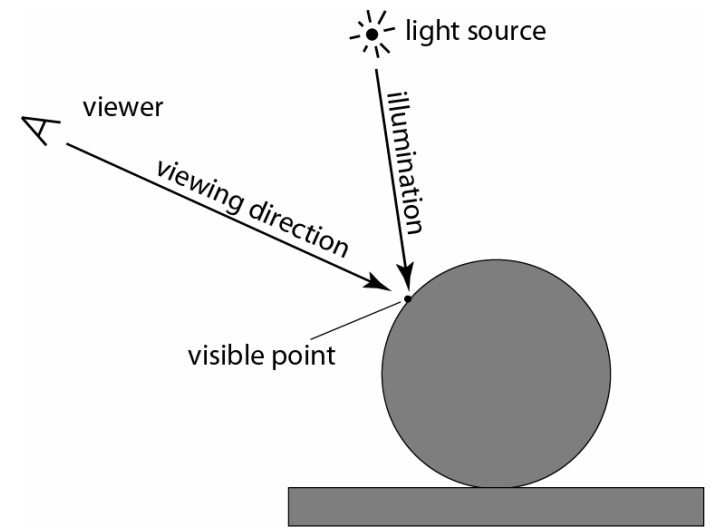
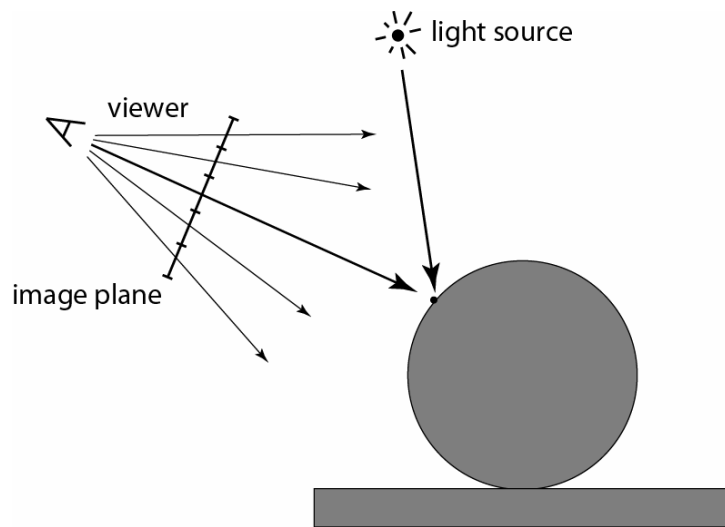


Image formation

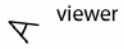


Rendering

Computational simulation of image formation.

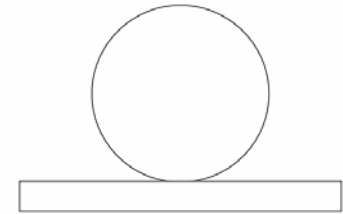
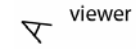
Rendering

- Given viewer



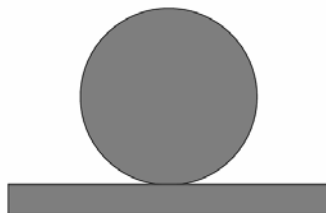
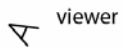
Rendering

- Given viewer, geometry



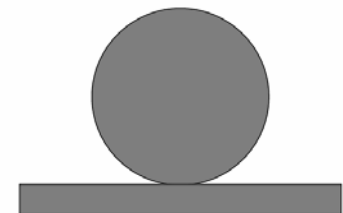
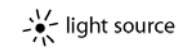
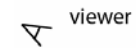
Rendering

- Given viewer, geometry, materials



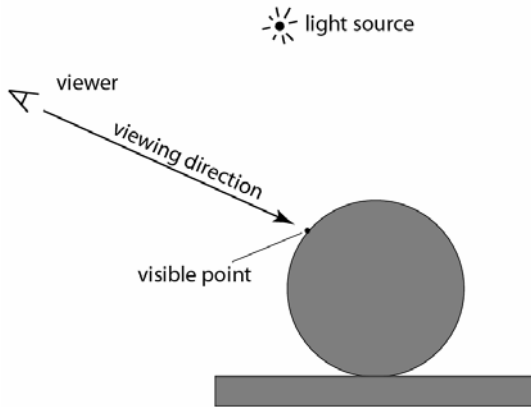
Rendering

- Given viewer, geometry, materials and lights



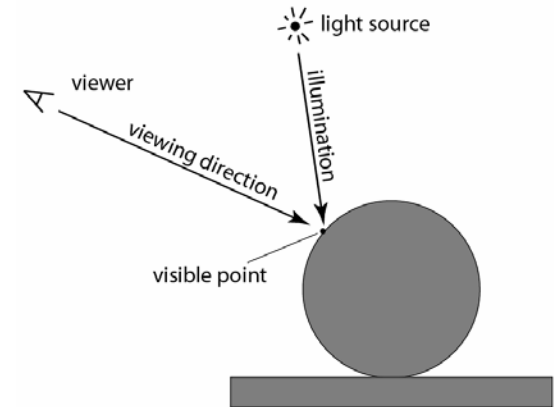
Rendering

- Given viewer, geometry, materials and lights
- Determine visibility



Rendering

- Given viewer, geometry, materials and lights
- Determine visibility and simulate lighting

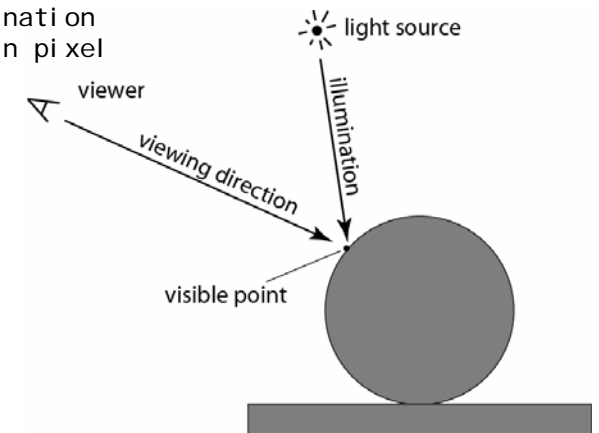


Ray Tracing

A particular rendering algorithm

Ray Tracing Algorithm

```
for each pixel {  
  determine viewing direction  
  intersect ray with scene  
  compute illumination  
  store result in pixel  
}
```



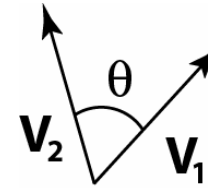
Vector math review - Points and Vectors

- Points
 - location in 3D space
 - $P = (x, y, z)$
- Vectors
 - direction and magnitude
 - $V = (u, v, w)$



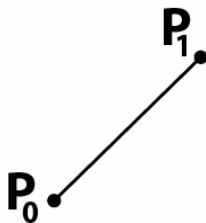
Vector math review - Vector operations

- Dot product
 - $V_1 \cdot V_2 = |V_1| |V_2| \cos(\theta)$
- Cross product
 - $|V_1 \times V_2| = |V_1| |V_2| \sin(\theta)$
 - $V_1 \times V_2$ is perpendicular to V_1 and V_2



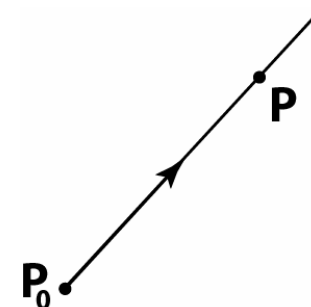
Vector math review - Segment and Rays

- Segment
 - set of points (line) between two points
 - $P(t) = P_0 + t (P_1 - P_0)$ with $t \in [0, 1]$



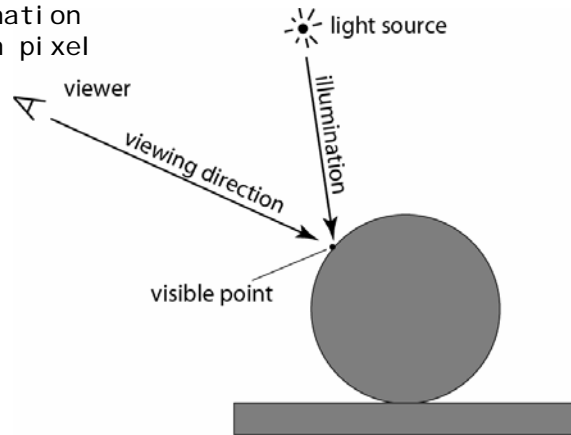
Vector math review - Segment and Rays

- Ray
 - infinite line from point in a given direction
 - $P(t) = P_0 + t V$ with $t \in [0, \infty]$



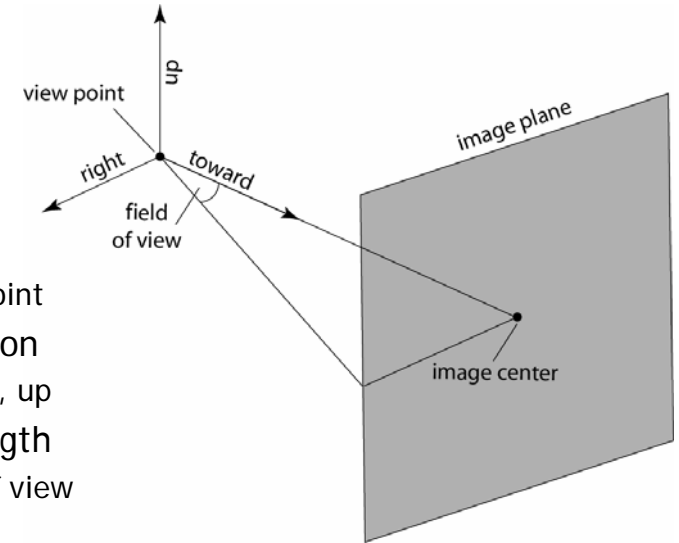
Ray Tracing Algorithm

```
for each pixel {  
  determine viewing direction  
  intersect ray with scene  
  compute illumination  
  store result in pixel  
}
```

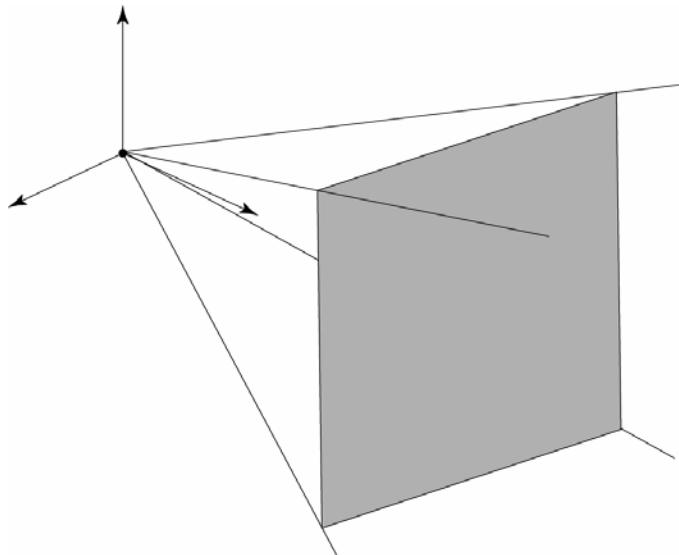


Viewer model - Representation

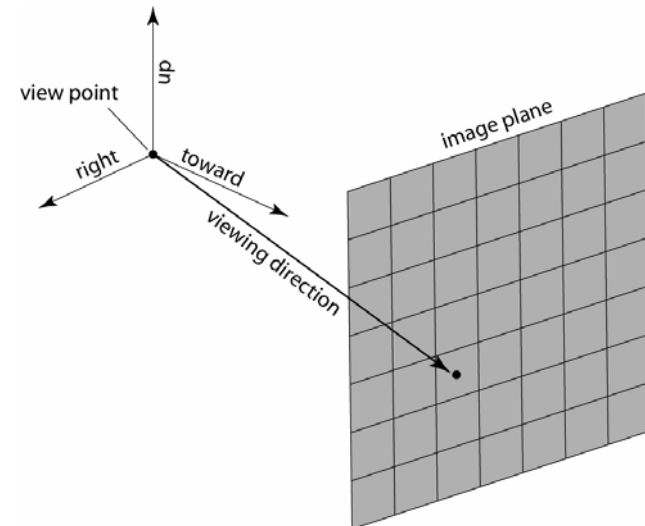
- position
 - view point
- orientation
 - toward, up
- focal length
 - field of view



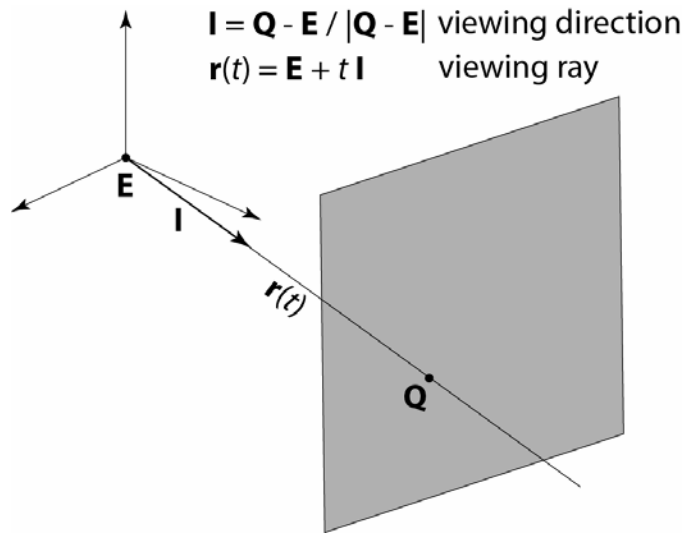
Viewer model - View frustum



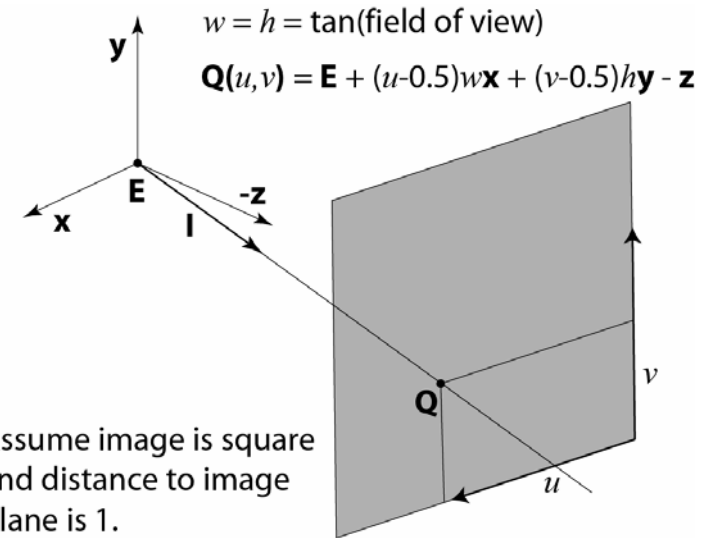
Generate viewing rays



Generate viewing rays



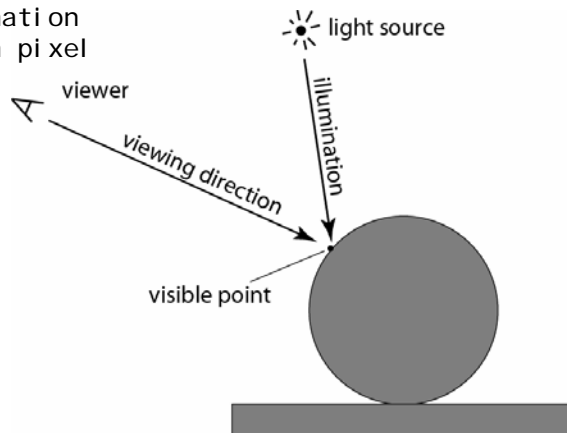
Generate viewing rays



Ray Tracing Algorithm

```

for each pixel {
  determine viewing direction
  intersect ray with scene
  compute illumination
  store result in pixel
}
    
```



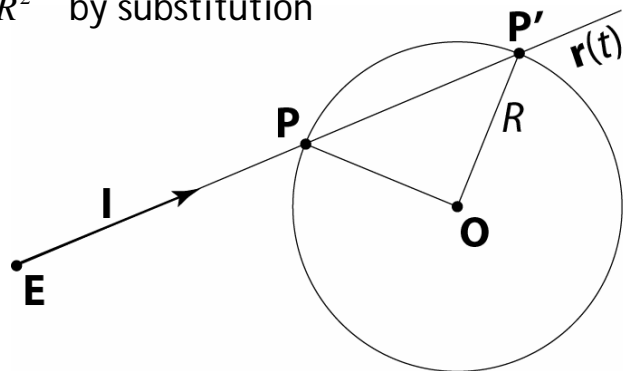
Geometry model

- Simple shapes
 - Spheres
 - Triangles
 - etc.
- Complex shapes
 - Later in the course

Ray-Sphere intersection - Algebraic

$$\begin{cases} \mathbf{P}(t) = \mathbf{E} + t\mathbf{I} & \text{point on ray} \\ |\mathbf{P}(t) - \mathbf{O}|^2 = R^2 & \text{point on sphere} \end{cases}$$

$$|\mathbf{E} + t\mathbf{I} - \mathbf{O}|^2 = R^2 \quad \text{by substitution}$$



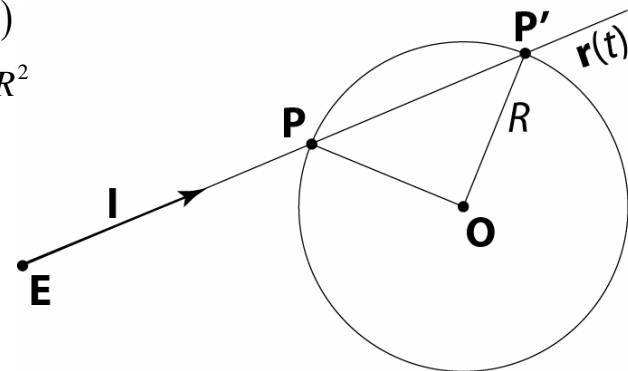
Ray-Sphere intersection - Algebraic

$$at^2 + bt + c = 0 \quad \text{algebraic equation}$$

$$a = |\mathbf{I}|^2$$

$$b = 2\mathbf{I} \cdot (\mathbf{E} - \mathbf{O})$$

$$c = |\mathbf{E} - \mathbf{O}|^2 - R^2$$



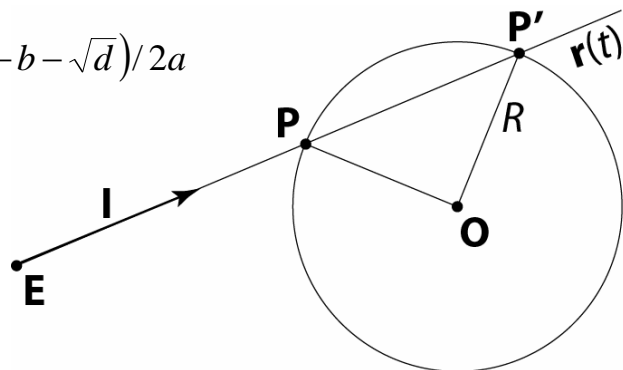
Ray-Sphere intersection - Algebraic

$$d = b^2 - 4ac \quad \text{determinant}$$

if $d < 0$ no solutions

otherwise

$$\mathbf{P}(t) \Leftrightarrow t_- = (-b - \sqrt{d}) / 2a$$

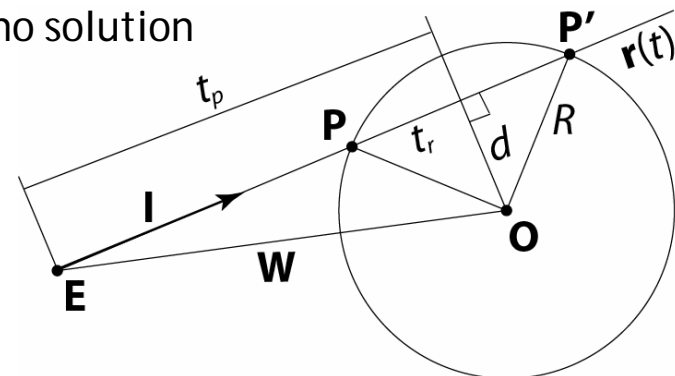


Ray-Sphere intersection - Geometric

$$\mathbf{W} = \mathbf{O} - \mathbf{E}$$

$$t_p = \mathbf{W} \cdot \hat{\mathbf{I}}$$

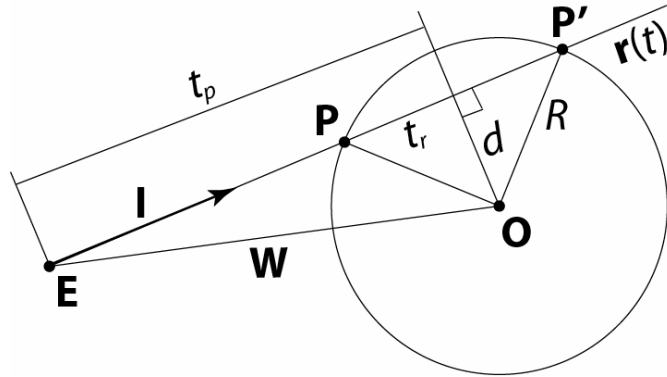
if $t_p < 0$ no solution



Ray-Sphere intersection - Geometric

$$d^2 = \mathbf{W} \cdot \mathbf{W} - t_p^2$$

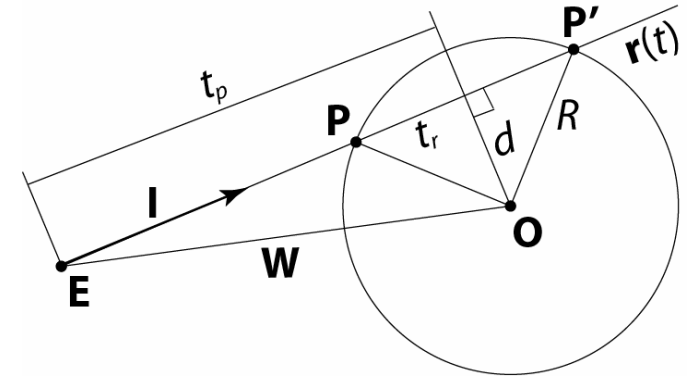
if $d^2 > R^2$ no solution



Ray-Sphere intersection - Geometric

$$t_r = \sqrt{R^2 - d^2}$$

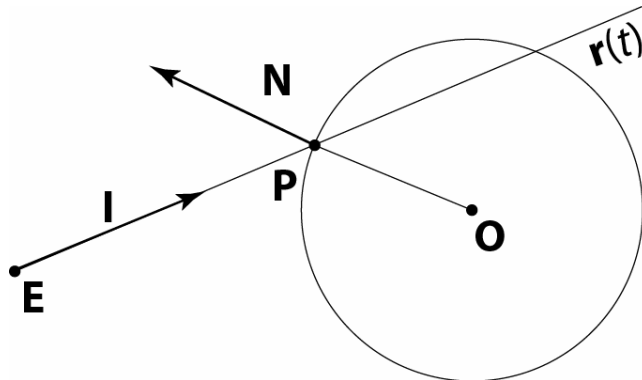
$$\mathbf{P}(t) \Leftrightarrow t_- = t_p - t_r$$



Ray-Sphere intersection - Normal

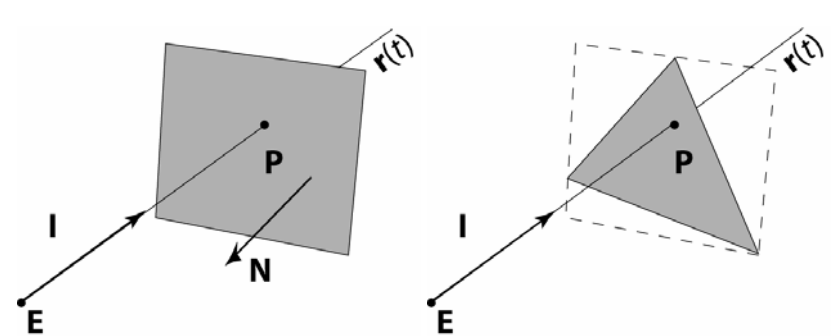
- Surface normal need for lighting computation

$$\mathbf{N} = (\mathbf{P} - \mathbf{O}) / |\mathbf{P} - \mathbf{O}|$$



Ray-Triangle intersection

- Intersect with a plane
- Check if the intersection point is in triangle



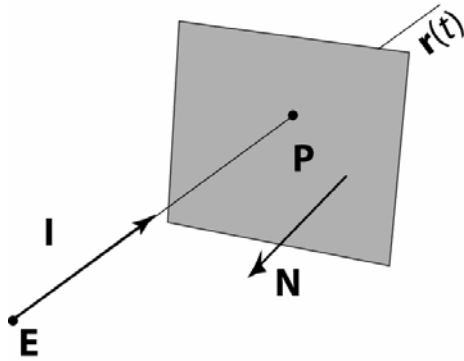
Ray-Plane intersection - Algebraic

$$\begin{cases} \mathbf{P}(t) = \mathbf{E} + t\mathbf{I} & \text{point on ray} \\ \mathbf{P} \cdot \mathbf{N} + d = 0 & \text{point on plane} \end{cases}$$

$$\mathbf{P} \cdot \mathbf{N} + d = 0 \quad \text{point on plane}$$

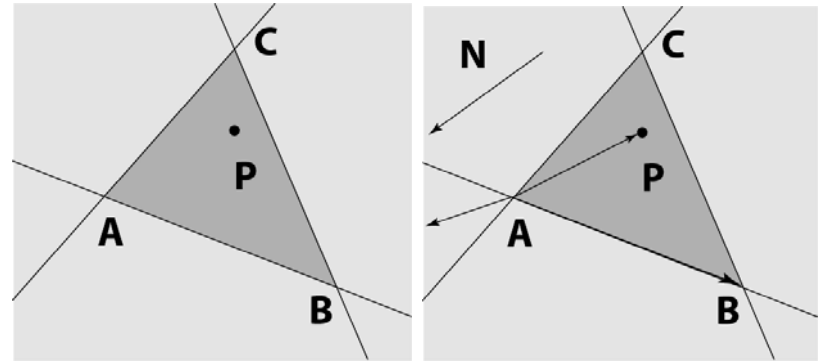
$$(\mathbf{E} + t\mathbf{I}) \cdot \mathbf{N} + d = 0 \quad \text{by substitution}$$

$$\mathbf{P}(t) \Leftrightarrow t = -\frac{\mathbf{E} \cdot \mathbf{N} + d}{\mathbf{I} \cdot \mathbf{N}}$$



Ray-Triangle intersection - Inside test

- Triangle is intersection of 3 half-spaces
- Check if P is on right side by comparing “normals”



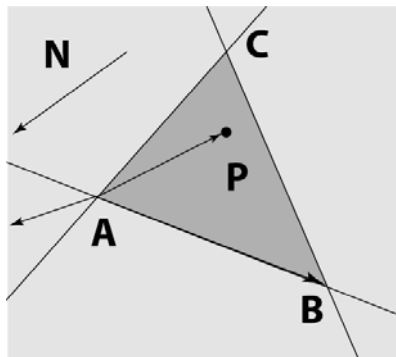
Ray-Triangle intersection - Inside test

intersects if

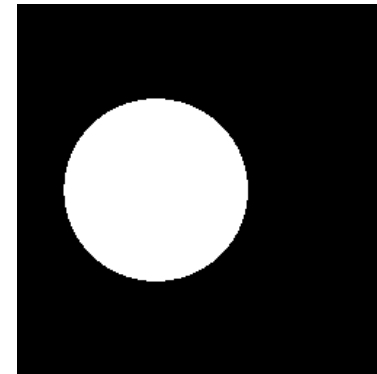
$$(\mathbf{B} - \mathbf{A}) \times (\mathbf{P} - \mathbf{A}) \cdot \mathbf{N} > 0$$

$$(\mathbf{C} - \mathbf{B}) \times (\mathbf{P} - \mathbf{B}) \cdot \mathbf{N} > 0$$

$$(\mathbf{A} - \mathbf{C}) \times (\mathbf{P} - \mathbf{C}) \cdot \mathbf{N} > 0$$

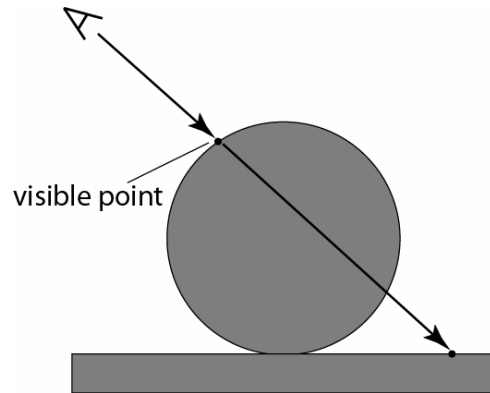


Images so far



Intersecting many shapes

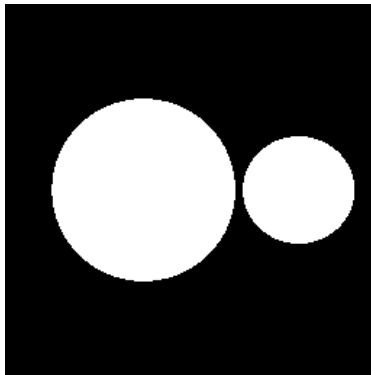
- Intersect each primitive
- Pick closest intersection



Intersecting many shapes - pseudocode

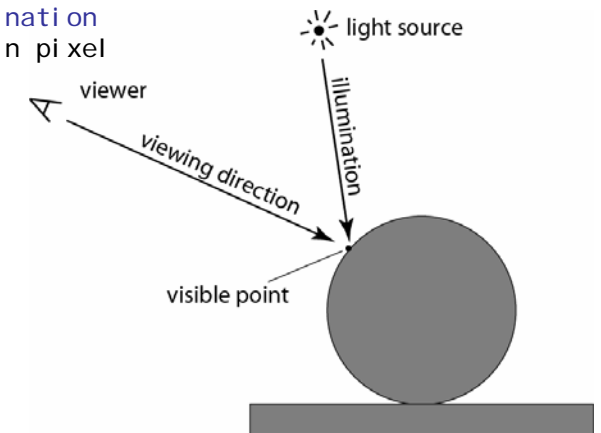
```
mi nDi stance = i nfi ni ty
hi t = fal se
foreach surface s {
  i f(s. i ntersect(ray, i ntersecti on)) {
    i f(i ntersecti on. di stance < mi nDi stance) {
      hi t = true;
      mi nDi stance = i ntersecti on. di stance;
    }
  }
}
```

Images so far



Ray Tracing Algorithm

```
for each pixel {
  determi ne vi ewi ng di recti on
  i ntersect ray wi th scene
  compute i l l u mi nati on
  store resul t i n pi xel
}
```



Shading

Variation in observed color across a surface

Lighting

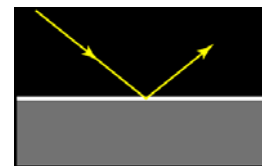
Patterns of illumination in the environment

Shading

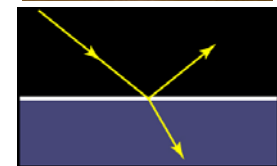
- compute reflected light
- depends on
 - viewer position
 - incoming light, i.e. lighting
 - surface geometry
 - surface material
- more on this later

Materials

metals

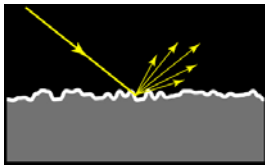


dielectric



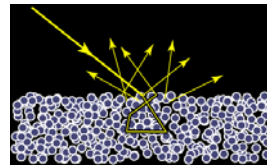
Materials

metals



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dielectric



[Marschner 2004]

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Shading models

- empirical shading models
 - produce believable images
 - simple and efficient
 - only for simple materials
- physically-based shading models
 - can reproduce accurate effects
 - more complex
- will concentrate empirical plastic-like model
 - more on this later in the course

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Phong shading model

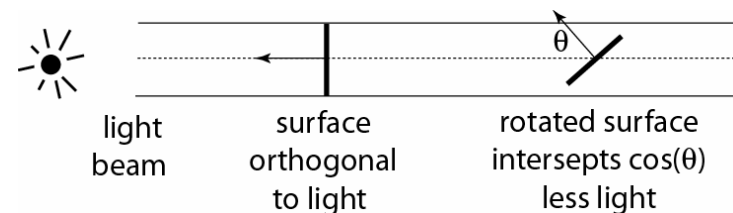
- shading model = diffuse + specular reflection
- diffuse reflection
 - light is reflected in every direction equally
 - colored by surface color
- specular reflection
 - light is reflected only around the mirror direction
 - white for plastic-like surfaces (glossy paints)
 - colored for metals (brass, copper, gold)

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Diffuse reflection

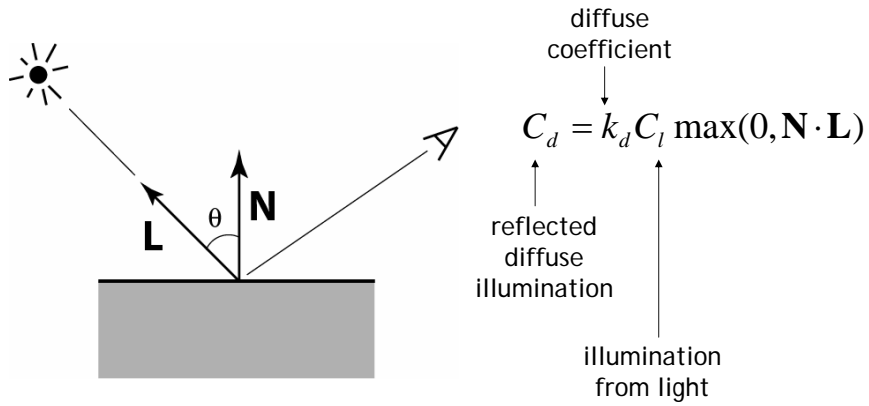
- Light reflects equally in all directions
 - i.e. surface looks the same from all view points
 - view-independent
- But incident light depends on angle
 - beam of light is more spread on an oblique surface



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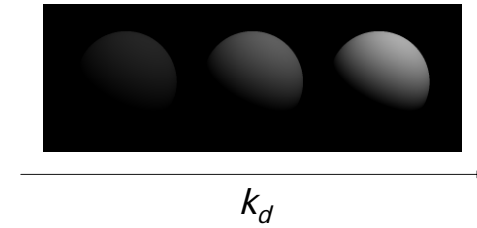
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Lambertian shading model

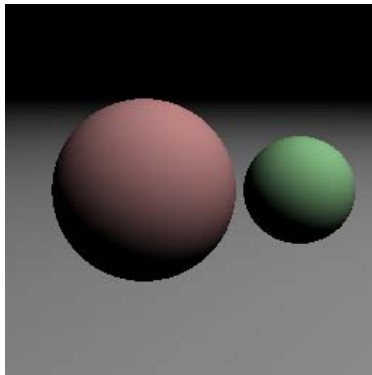


Lambertian shading model

- Produces matte appearance



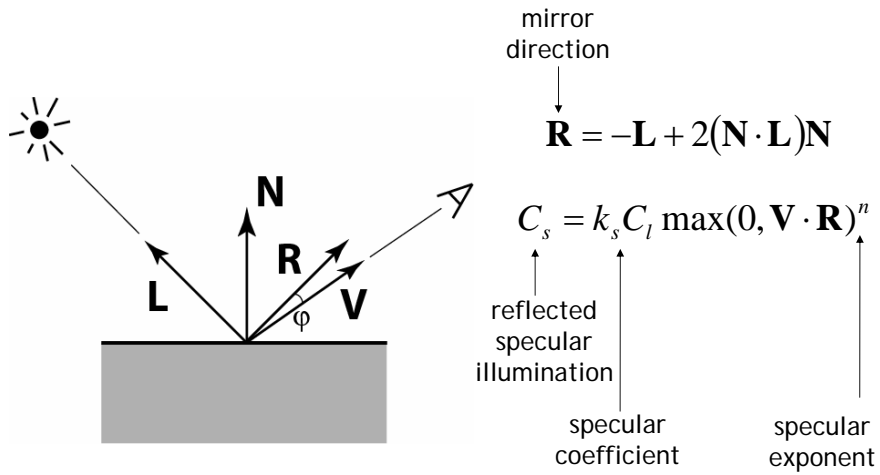
Images so far



Specular shading

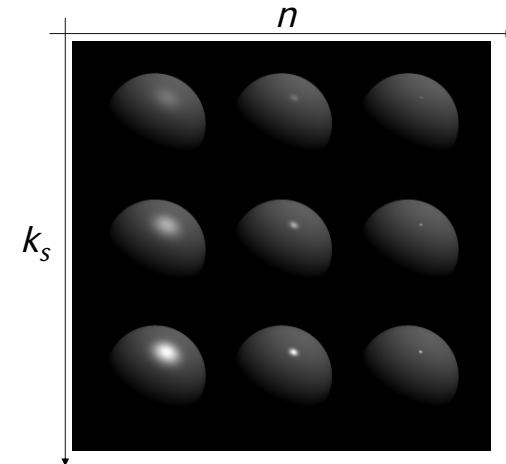
- Light reflects mostly around mirror direction
 - i.e. surface looks different from view points
 - view-dependent
- Phong specular model
 - empirical, but looks good enough
 - use cosine of mirror and view direction
- Blinn-Phong specular model
 - slightly better than Phong
 - use cosine of bisector and normal direction

Phong specular model

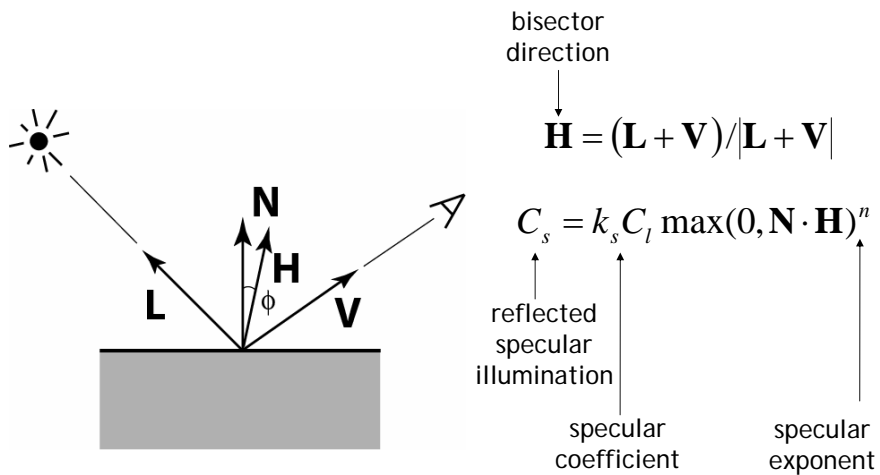


Phong specular model

- Produces highlights, shiny appearance



Blinn-Phong variation



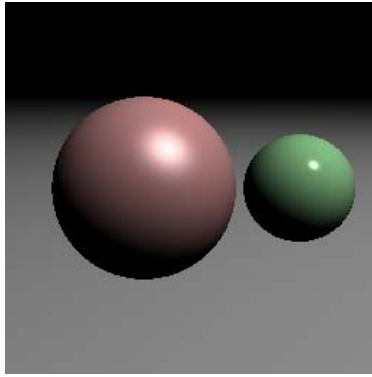
Shading model

- Putting the pieces together

$$C = C_d + C_s =$$

$$= C_l \left[k_d \max(0, \mathbf{N} \cdot \mathbf{L}) + k_s \max(0, \mathbf{V} \cdot \mathbf{R})^n \right]$$

Images so far



Lighting

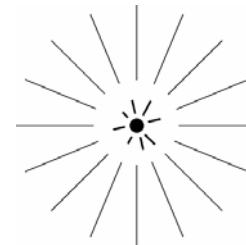
- determines how much light reaches a point
- depends on
 - light geometry
 - light emission
 - scene geometry

Light source models

- describe how light is emitted from light sources
- empirical light source models
 - point, directional, spot
- physically-based light source models
 - area lights, sky model
 - will cover later in the course

Light source models - Point lights

- light emitted equally from point in all directions
 - simulates local lights
 - sometimes r^2 falloff for a bit more realism

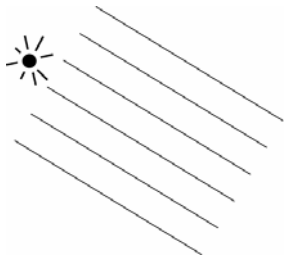


$$L = \|\mathbf{S} - \mathbf{P}\|$$

$$C_l = C / r^2$$

Light source models - Directional lights

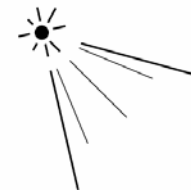
- light emitted from infinity in one direction
 - simulates distant lights, e.g. sun



$$\mathbf{L} = \mathbf{D}$$
$$C_l = C$$

Light source models - Spot lights

- same as point light, but only emit in a cone
 - simulate theatrical lights
 - cone falloff model arbitrary



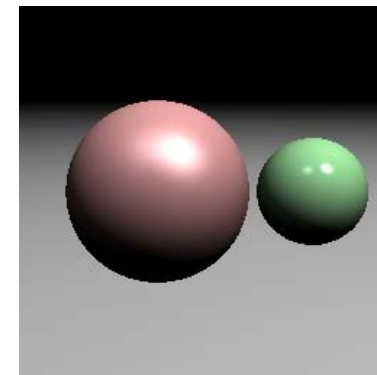
$$\mathbf{L} = \|\mathbf{S} - \mathbf{P}\|$$
$$C_l = C \cdot att / r^2$$

Multiple lights

- add contribution for each light

$$C = \sum_i (C_d)_i + (C_s)_i =$$
$$= \sum_i (C_l)_i \left[k_d \max(0, \mathbf{N} \cdot (\mathbf{L})_i) + k_s \max(0, \mathbf{V} \cdot (\mathbf{R})_i)^n \right]$$

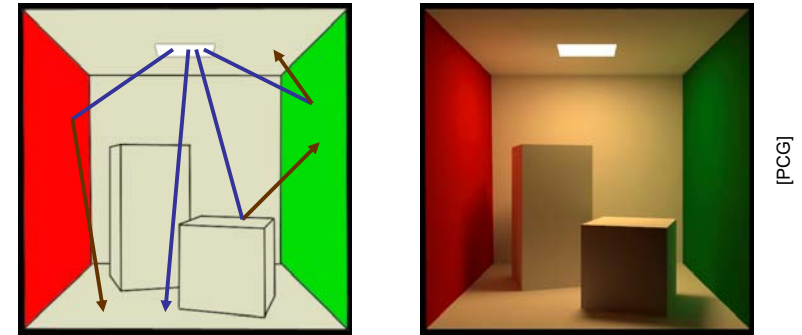
Image so far



Illumination models

- describe how light spreads in the environments
- direct illumination
 - incoming lights comes directly from sources
 - shadows
- indirect illumination
 - incoming lights comes from other objects
 - specular reflections (mirrors), diffuse inter-reflections

Illumination models

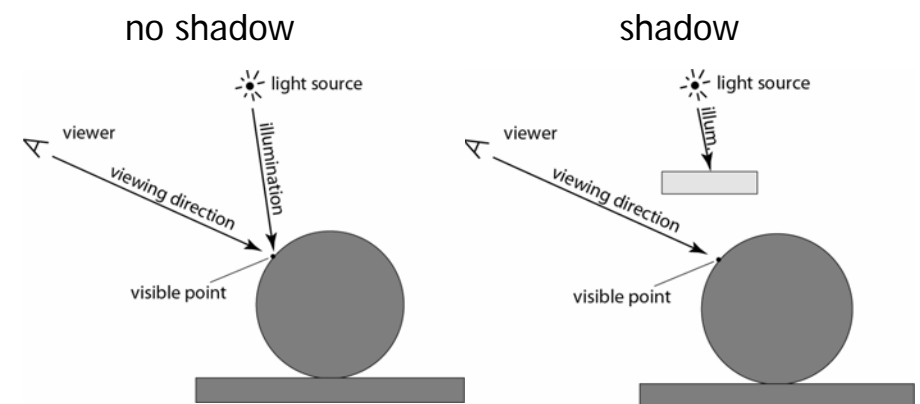


Ray Tracing lighting model

- captures
 - point/directional/spot light source models
 - sharp shadows
 - sharp reflections/refractions
 - hacked diffuse inter-reflections: ambient term
- more accurate lighting later in the course

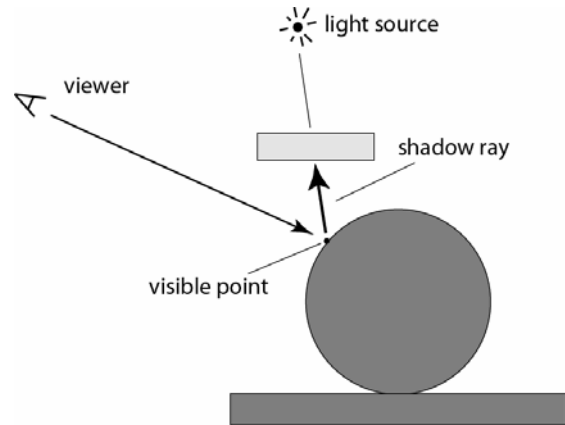
Ray Traced Shadows

- light contributes only if visible at surface point



Ray Traced Shadows

- cast a “shadow-ray” to check if light is visible
- visible if no-hits or if distance > light distance



Ray Traced Shadows

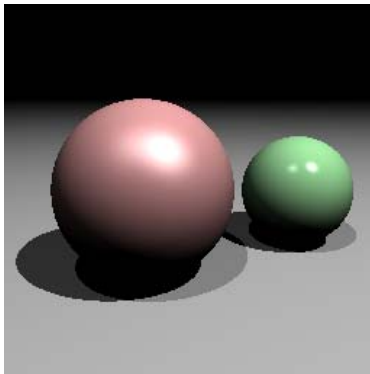
- scale light by a visibility term

$$C = \sum_i (C_d)_i + (C_s)_i =$$

$$= \sum_i (C_l)_i V_i(\mathbf{P}) [k_d \max(0, \mathbf{N} \cdot (\mathbf{L})_i) + k_s \max(0, \mathbf{V} \cdot (\mathbf{R})_i)^n]$$

↑
light source
visibility {0,1}

Images so far



Ambient term hack

- light bounces even in diffuse environment
 - ceiling are not black
 - shadows are not perfectly black
- very expensive to compute
- approximate (poorly) with a constant term

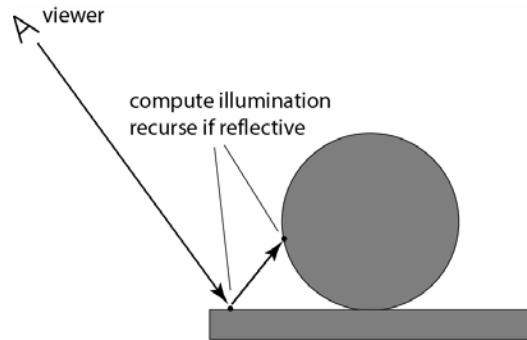
$$C = C_a + \sum_i [(C_d)_i + (C_s)_i] =$$

$$= k_a C_{amb} + \sum_i [(C_d)_i + (C_s)_i]$$

↑ ↑
ambient ambient
coefficient illumination

Ray Traced Reflections

- perfectly shiny surfaces reflects objects
 - recursively trace a ray if material is reflective
 - along mirror direction, scaled by reflection coeff.
 - mirror direction calculated for Phong



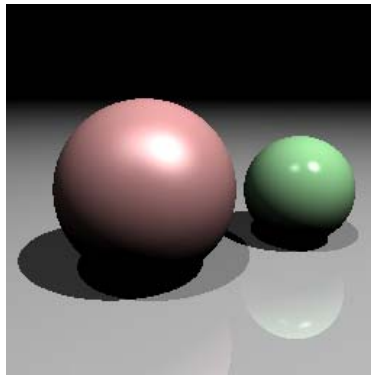
Ray Traced Reflections

- recursively ray trace, scale by reflection coeff.
- refraction is the same along the transmission dir.

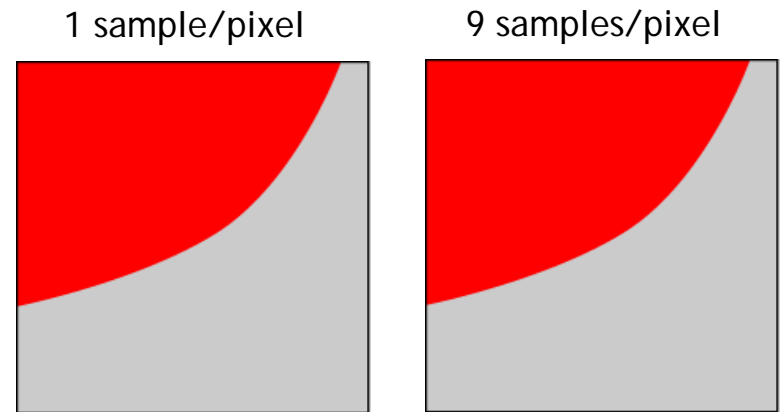
$$\begin{aligned}
 C &= C_a + \sum_i [(C_d)_i + (C_s)_i] + C_r + C_t = \\
 &= C_a + \sum_i [(C_d)_i + (C_s)_i] + \\
 &\quad + k_r \text{raytrace}(\mathbf{P}, \mathbf{R}) + k_t \text{raytrace}(\mathbf{P}, \mathbf{T})
 \end{aligned}$$

↑ reflection coefficient ↑ refraction coefficient

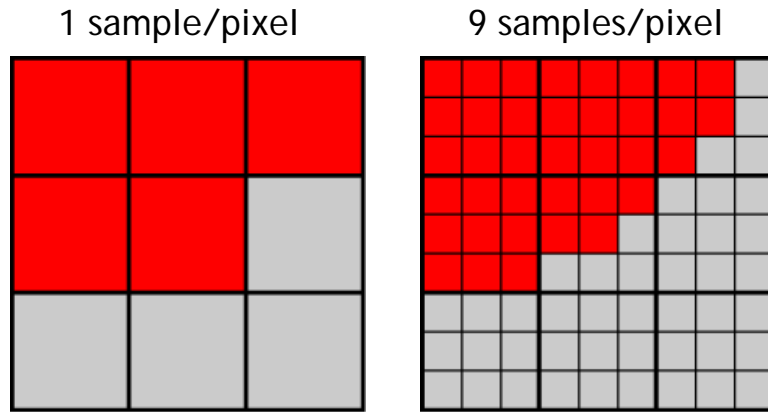
Images so far



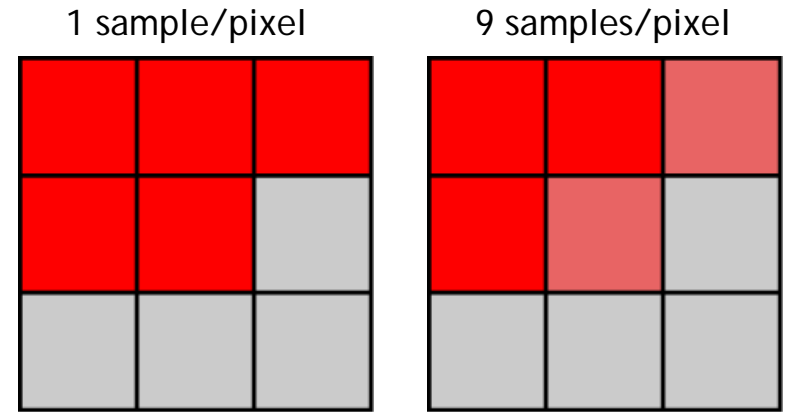
Antialiasing - Removing jaggies



Antialiasing - Removing jaggies



Antialiasing - Removing jaggies



Antialiasing - Removing jaggies

- for each pixel
 - take multiple samples
 - compute average
- poor-man antialiasing
 - more on this later in the course

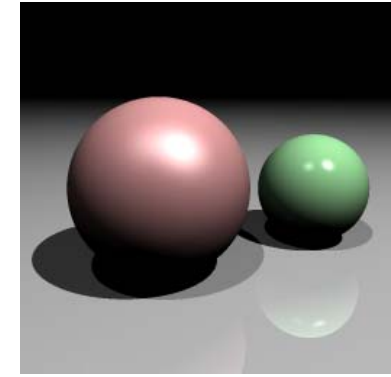
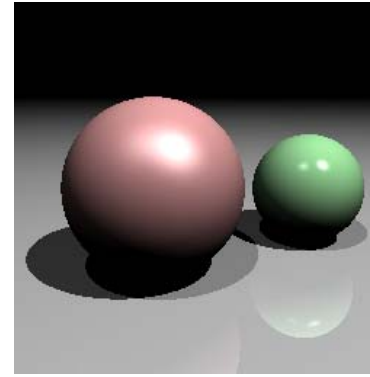
Ray Tracing Pseudocode

```
for(i = 0; i < imageWidth; i++) {  
  for(j = 0; j < imageHeight; j++) {  
    u = (i + 0.5)/imageWidth;  
    v = (j + 0.5)/imageHeight;  
    ray = camera.generateRay(u, v);  
    c = computeColor(ray);  
    image[i][j] = c;  
  }  
}
```

Antialiased Ray Tracing Pseudocode

```
for(i = 0; i < imageWidth; i++) {
  for(j = 0; j < imageHeight; j++) {
    color c = 0;
    for(ii = 0; ii < numberOfSamples; ii++) {
      for(jj = 0; jj < numberOfSamples; jj++) {
        x = (i+(ii+0.5)/numberOfSamples)/imageWidth;
        y = (j+(jj+0.5)/numberOfSamples)/imageHeight;
        ray = camera.generateRay(x, y);
        c += computeColor(ray);
      }
    }
    image[i][j] = c / (numberOfSamples^2);
  }
}
```

Images so far



Ray Tracing details

- Numerical precision issues can come up
 - Shadow acne: ray hits the visible point
 - Solution: only intersect if distance > epsilon
- Make sure you do not recurse infinitely when computing reflections or refractions
 - Solution: Simply stop after a given number

Ray Tracing wrap-up

- simple and general algorithm
 - ray cast to evaluate visibility
 - simplified shading model
 - ray cast to evaluate shadows
 - recursive execution for reflections/refractions
- inefficient - linear with number of primitives
 - sub-linear ray cast later in the course
- not photorealistic - too clean
 - missing soft shadows, realistic materials, realistic camera model, diffuse inter-reflection
- **base of most general algorithms**